# S1 Algorithm. Pseudo-code of ToPs/R

#### Off-line Stage 0: Dividing the dataset (D)

**Input:** Entire dataset D

**Divide** D into disjoint training set (S), the first validation set  $(V^1)$ , the second validation set  $(V^2)$  and testing set (T) which satisfy  $D = S \cup V^1 \cup V^2 \cup T$ **Output:** Training set S, validation sets  $V^1, V^2$ , and testing set T

### Off-line Stage 1: Growing the Optimal Tree of Predictors

**Input:** Feature space X, a set of algorithms  $\mathcal{A}$ , training set S, the validation set  $V^1$ **First step:** Initial tree of predictors =  $(X, h_X)$  where  $h_X = \arg \min_{A \in \mathcal{A}}$ **Recursive step:** 

**Input:** Current tree of predictors  $(T, \{h_C\})$ 

for each terminal node  $C \in T$  do

for a feature i and a threshold  $\tau_i$  do

Set  $C^{-}(\tau_{i}) = \{x \in C : x_{i} < \tau_{i}\}, C^{+}(\tau_{i}) = \{x \in C : x_{i} \geq \tau_{i}\}$ , Then,  $\{i^{*}, \tau_{i}^{*}, h_{C^{-}(\tau_{i}^{*})}, h_{C^{+}(\tau_{i}^{*})}\} = \arg \min \mathcal{L}(h^{-} \cup h^{+}, V^{1}(C^{-}(\tau_{i})) \cup V^{1}(C^{+}(\tau_{i})))$ where  $h^{-} \in A(C^{-}(\tau_{i})^{\uparrow}), h^{+} \in A(C^{+}(\tau_{i})^{\uparrow})$ 

Stopping Criteria:  $\mathcal{L}(h_C, V^1(C)) \leq \min \mathcal{L}(h^- \cup h^+, V^1(C^-(\tau_i)) \cup V^1(C^+(\tau_i)))$ Output: Locally optimal tree of predictors  $(T, \{h_C\})$ 

# Off-line Stage 2: Weights Optimization on the Path

**Input:** Locally optimal tree of predictors  $(T, \{h_C\})$ , the second validation set  $V^2$ for each terminal node  $\bar{C}$  and the corresponding path  $\Pi$  from X to  $\bar{C}$  do

for each weight vector  $w = (w_C)$ , do

Define  $H_w = \sum_{C \in \Pi} w_C h_C$ , Then,

 $w^*(\Pi) = (w^*(\Pi, \vec{C})) = \arg\min \mathcal{L}(H_w, V^2(\vec{C}))$ 

**Output:** Optimized weights  $w^*(\Pi)$  for each terminal node  $\overline{C}$  and corresponding path  $\Pi$ 

# **On-line Stage: Overall Predictor**

**Input:** Locally optimal tree of predictors  $(T, \{h_C\})$ , optimized weights  $w^*(\Pi)$ , and testing set T

Given a feature vector x

Find the unique path  $\Pi(x)$  from X to terminal node containing x

Then,  $H(x) = \sum_{C \in \Pi(x)} w^*(\Pi, C) h_C(x)$ 

**Output:** The final prediction H(x)