CORRECTION

Correction: Learning Probabilistic Features for Robotic Navigation Using Laser Sensors

The *PLOS ONE* Staff

The following information is missing from the Funding section: This work was also supported by the Spanish Ministerio de Economía y Competitividad, project TIN2013-40982-R.

Reference

1. Aznar F, Pujol FA, Pujol M, Rizo R, Pujol M-J (2014) Learning Probabilistic Features for Robotic Navigation Using Laser Sensors. PLoS ONE 9(11): e112507. doi: [10.1371/journal.pone.0112507](https://doi.org/10.1371/journal.pone.0112507) PMID: [25415377](https://pubmed.ncbi.nlm.nih.gov/25415377/)

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