CORRECTION

## Correction: Coherent detection-based photonic radar for autonomous vehicles under diverse weather conditions

The PLOS ONE Staff

There is information missing from the Funding statement. The publisher apologizes for the error. The correct Funding statement is as follows: This research project is supported by the Second Century Fund (C2F), Chulalongkorn University, Thailand. This research work is also funded by TSRI Fund (CU\_FRB640001\_01\_21\_8). This project is also supported by Taif University Researchers supporting project number (TURSP-2020/228), Taif University, Taif, Saudi Arabia. The funders had no role in study design, data collection and analysis, decision to publish, or preparation of the manuscript.

## Reference

Chaudhary S, Wuttisittikulkij L, Saadi M, Sharma A, Al Otaibi S, Nebhen J, et al. (2021) Coherent detection-based photonic radar for autonomous vehicles under diverse weather conditions. PLoS ONE 16 (11): e0259438. https://doi.org/10.1371/journal.pone.0259438 PMID: 34780504



## 

**Citation:** The *PLOS ONE* Staff (2021) Correction: Coherent detection-based photonic radar for autonomous vehicles under diverse weather conditions. PLoS ONE 16(11): e0260799. <u>https://</u> doi.org/10.1371/journal.pone.0260799

Published: November 29, 2021

**Copyright:** © 2021 The PLOS ONE Staff. This is an open access article distributed under the terms of the Creative Commons Attribution License, which permits unrestricted use, distribution, and reproduction in any medium, provided the original author and source are credited.