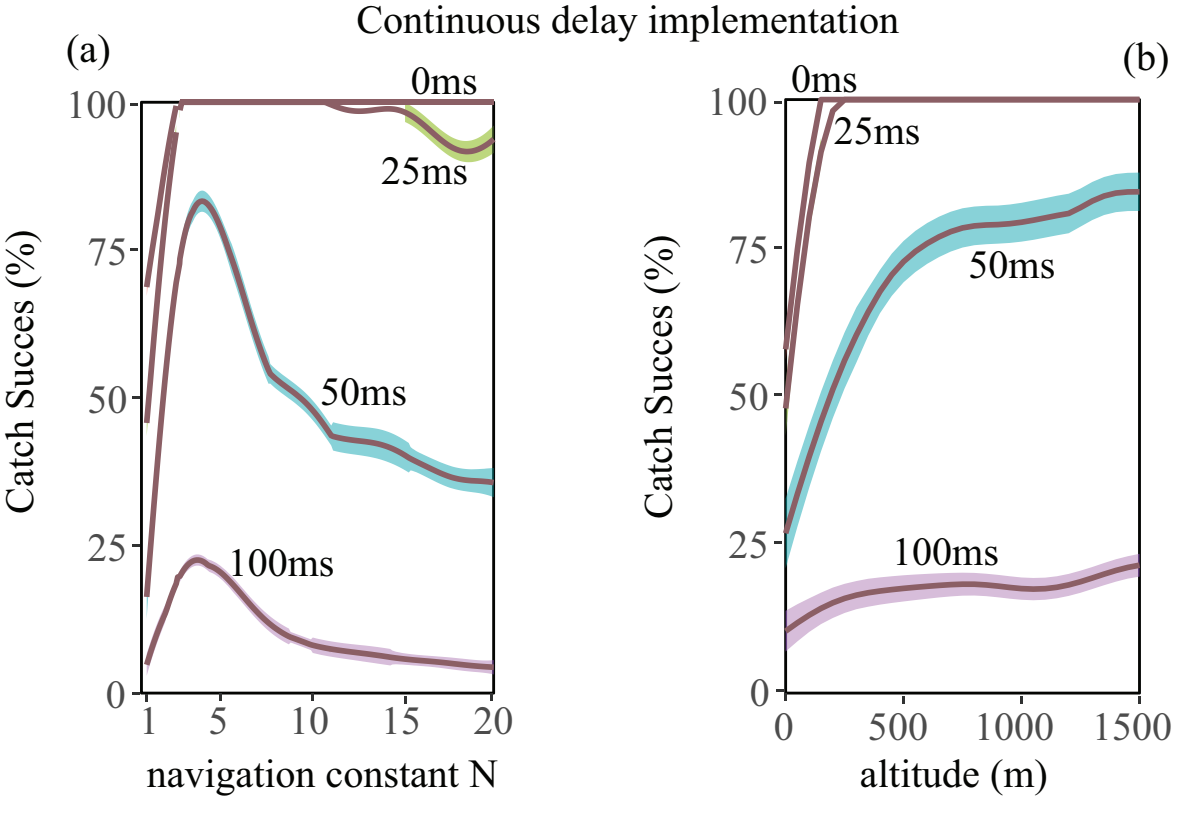
Continuous delay implementation
(a)
(b)
0ms
25ms
50ms
100ms
Catch Succes (%)
navigation constant N
altitude (m)
0
25
50
75
100
1
5
10
15
20
500
1000
1500