

Text S3: Supporting Information for

Coordinated optimization of visual cortical maps

(I) Symmetry-based analysis

Stability matrix

Here, we state the stability matrices M used in the linear stability analysis of the coupled amplitude equations. The stability matrix is defined by

$$\partial_t \begin{pmatrix} \text{Re}A_i \\ \text{Re}A_{i-} \\ \text{Im}A_i \\ \text{Im}A_{i-} \end{pmatrix} = M \begin{pmatrix} \text{Re}A_i \\ \text{Re}A_{i-} \\ \text{Im}A_i \\ \text{Im}A_{i-} \end{pmatrix} = \begin{pmatrix} M1 & M2 \\ M3 & M4 \end{pmatrix} \begin{pmatrix} \text{Re}A_i \\ \text{Re}A_{i-} \\ \text{Im}A_i \\ \text{Im}A_{i-} \end{pmatrix}$$

for the uniform solutions Eq. (60). We separate the uncoupled contributions from the inter-map coupling contributions i.e. $M1 = M1^{(u)} + M1^{(\alpha)}$. The uncoupled contributions are given by

$$M1^{(u)} = r_z \mathbf{I} + \mathcal{A}^2 \begin{pmatrix} -13 & -3 & 3 & -2c & -3c - \sqrt{3}s & 3c - \sqrt{3}s \\ -3 & -23/2 & 0 & -3c - \sqrt{3}s & -2c & 0 \\ 3 & 0 & -23/2 & 3c - \sqrt{3}s & 0 & -2c \\ -2c & -3c - \sqrt{3}s & 3c - \sqrt{3}s & -12 - \cos 2\Delta & -2 - 2u & 2 + 2v \\ -3d + \sqrt{3}s & -2d & 0 & -2 - 2u & -12 - \cos(2\Delta + 10\pi/3) & -4d^2 \\ 3c - \sqrt{3}s & 0 & -2c & -2 - 2v & -4s^2 & -12 + u \end{pmatrix}$$

$$M2^{(u)} = \mathcal{A}^2 \begin{pmatrix} 0 & \sqrt{3} & \sqrt{3} & 2s & 2 \cos(\Delta - \pi/6) & 2 \cos(\Delta + \pi/6) \\ \sqrt{3} & \sqrt{3}/2 & 0 & 2 \cos(\Delta - \pi/6) & 2s & 4s \\ \sqrt{3} & 0 & -\sqrt{3}/2 & 2 \cos(\Delta + \pi/6) & 4s & 2s \\ -2s & \sqrt{3}d - 3s & \sqrt{3}d + 3s & -\sin 2\Delta & 2x & 2y \\ \sqrt{3}d - 2s & -2d & 0 & 2x & y & 2 \sin 2\Delta \\ \sqrt{3}d + 3s & 0 & -2s & 2y & 2 \sin 2\Delta & -x \end{pmatrix}$$

$$M3^{(u)} = \mathcal{A}^2 \begin{pmatrix} 0 & \sqrt{3} & \sqrt{3} & 2s & 2\cos(\Delta - \pi/6) & 2\cos(\Delta + \pi/6) \\ \sqrt{3} & \sqrt{3}/2 & 0 & 2\cos(\Delta - \pi/6) & 2s & 4s \\ \sqrt{3} & 0 & -\sqrt{3}/2 & 2\cos(\Delta + \pi/6) & 4s & 2s \\ -2s & \sqrt{3}c - 3s & \sqrt{3}c + 3s & -\sin 2\Delta & 2x & 2y \\ \sqrt{3}d - 3s & -2s & 0 & 2x & y & 2\sin 2\Delta \\ \sqrt{3}c + 3s & 0 & -2s & 2y & 2\sin 2\Delta & -x \end{pmatrix}$$

$$M4^{(u)} = r_z \mathbf{I} + \mathcal{A}^2 \begin{pmatrix} -11 & -1 & 1 & -2c & 2w & 2z \\ -1 & -25/2 & -4 & 2w & -2c & -4c \\ 1 & -4 & -25/2 & 2z & -4c & -2c \\ -2c & 2w & 2z & -12 + \cos 2\Delta & 2(u-1) & 2(1+v) \\ 2w & -2c & -4c & 2(u-1) & -12 + \cos(2\Delta + 10\pi/3) & -4c^2 \\ 2z & -4c & -2c & 2(v+1) & -4c^2 & -12 + \cos(2\Delta + 8\pi/3), \end{pmatrix}$$

where \mathbf{I} denotes the 6×6 identity matrix and $s = \sin \Delta, c = \cos \Delta, u = \sin(2\Delta + \pi/6), v = \sin(2\Delta - \pi/6), x = \cos(2\Delta + \pi/6), y = \cos(2\Delta - \pi/6), w = \sin(\Delta - \pi/6), z = \sin(\Delta + \pi/6)$.

The coupling part in case of the low order product-type inter-map coupling energy is given by

$$M1^{(\alpha)} = \alpha \begin{pmatrix} -(6\mathcal{B}^2 + \delta^2) & 2\mathcal{B}^2 & -2\mathcal{B}^2 & -\mathcal{B}^2 & 2\mathcal{B}(\mathcal{B} - \delta) & -2\mathcal{B}(\mathcal{B} - \delta) \\ 2\mathcal{B}^2 & -(6\mathcal{B}^2 + \delta^2) & 2\mathcal{B}^2 & 2\mathcal{B}(\mathcal{B} - \delta) & -\mathcal{B}^2 & 2\mathcal{B}(\mathcal{B} - \delta) \\ -2\mathcal{B}^2 & 2\mathcal{B}^2 & -(6\mathcal{B}^2 + \delta^2) & 2\mathcal{B}(-\mathcal{B} + \delta) & 2\mathcal{B}(\mathcal{B} - \delta) & -\mathcal{B}^2 \\ -\mathcal{B}^2 & 2\mathcal{B}(\mathcal{B} - \delta) & -2\mathcal{B}(\mathcal{B} - \delta) & -(6\mathcal{B}^2 + \delta^2) & 2\mathcal{B}^2 & -2\mathcal{B}^2 \\ 2\mathcal{B}^2(\mathcal{B} - \delta) & -\mathcal{B}^2 & 2\mathcal{B}(\mathcal{B} - \delta) & 2\mathcal{B}^2 & -(6\mathcal{B}^2 + \delta^2) & 2\mathcal{B}^2 \\ 2\mathcal{B}(-\mathcal{B} + \delta) & 2\mathcal{B}(\mathcal{B} - \delta) & -\mathcal{B}^2 & -2\mathcal{B}^2 & 2\mathcal{B}^2 & -(6\mathcal{B}^2 + \delta^2) \end{pmatrix}$$

$$M4^{(\alpha)} = M1^{(\alpha)}, M2^{(\alpha)} = M3^{(\alpha)} = 0.$$

The coupling part in case of the low order gradient-type inter-map coupling energy is given by

$$M1^{(\beta)} = \beta \mathcal{B}^2 \begin{pmatrix} 3 & -5/4 & 5/4 & 1 & -5/4 & 5/4 \\ -5/4 & 3 & -5/4 & -5/4 & 1 & -5/4 \\ 5/4 & -5/4 & 3 & 5/4 & -5/4 & 1 \\ 1 & -5/4 & 5/4 & 3 & -5/4 & 5/4 \\ -5/4 & 1 & -5/4 & -5/4 & 3 & -5/4 \\ 5/4 & -5/4 & 1 & 5/4 & -5/4 & 3 \end{pmatrix}$$

$$M4^{(\beta)} = M1^{(\beta)}, M2^{(\beta)} = M3^{(\beta)} = 0.$$

The stationary amplitudes \mathcal{A} are given in Eq. (63), Eq. (68), Eq. (81), and Eq. (83). The stationary amplitudes \mathcal{B} and the constant δ are given by Eq. (94) and Eq. (116), respectively.