## **Supplemental Text for: Adaptable Functionality of Transcriptional Feedback in Bacterial Two-Component Systems** by J. Christian J. Ray and Oleg A. Igoshin

## Text S2: Partitioned Monte Carlo sampling in a simplified model

Monte Carlo sampling in the main text explores a 21-dimensional parameter space, making extensive coverage of the space impractical. To more extensively explore the parameter space and further test our conclusions that (i) overshoot occurs with negative open-loop gain or (ii) negative open-loop gain requires exogenous phosphorylation, we simplified the model. Any reactions not strictly necessary to demonstrate overshoot and negative open-loop gain were removed. The resulting simplified model has 13 parameters in the sample space (Figure S3A). We partitioned each parameter into 4 intervals, and sampled each once. This resulted in a sampling of 67,108,864 discrete regions of parameter space. We discarded cases that cause numerical computation errors . Figure S3B shows the distribution of exogenous phosphorylation ratios  $J_E/(J_E + J_S)$  (fractions of RR phosphorylation not from cognate SHK) to have a lower bound of approximately  $10^{-4}$  for effectively negative feedback<sup>1</sup> (open-loop gain

$$\frac{\partial [\text{RRP}_2]}{\partial [\text{R}_0]}\Big|_{k_{ph}=0.1} < -0.01 \text{ ) but not for positive } \left( \left. \frac{\partial [\text{RRP}_2]}{\partial [\text{R}_0]} \right|_{k_{ph}=0.1} > 0.01 \text{ ) . All cases found to exhibit feedback-} \right|_{k_{ph}=0.1} < -0.01 \text{ ) but not for positive } \left( \left. \frac{\partial [\text{RRP}_2]}{\partial [\text{R}_0]} \right|_{k_{ph}=0.1} > 0.01 \text{ ) but not for positive } \left( \left. \frac{\partial [\text{RRP}_2]}{\partial [\text{R}_0]} \right|_{k_{ph}=0.1} > 0.01 \text{ ) but not for positive } \left( \left. \frac{\partial [\text{RRP}_2]}{\partial [\text{R}_0]} \right|_{k_{ph}=0.1} > 0.01 \text{ ) but not for positive } \left( \left. \frac{\partial [\text{RRP}_2]}{\partial [\text{R}_0]} \right|_{k_{ph}=0.1} > 0.01 \text{ ) but not for positive } \left( \left. \frac{\partial [\text{RRP}_2]}{\partial [\text{R}_0]} \right|_{k_{ph}=0.1} > 0.01 \text{ ) but not for positive } \left( \left. \frac{\partial [\text{RRP}_2]}{\partial [\text{R}_0]} \right|_{k_{ph}=0.1} > 0.01 \text{ ) but not for positive } \left( \left. \frac{\partial [\text{RRP}_2]}{\partial [\text{R}_0]} \right|_{k_{ph}=0.1} > 0.01 \text{ ) but not for positive } \left( \left. \frac{\partial [\text{RRP}_2]}{\partial [\text{R}_0]} \right|_{k_{ph}=0.1} > 0.01 \text{ ) but not for positive } \left( \left. \frac{\partial [\text{RRP}_2]}{\partial [\text{R}_0]} \right|_{k_{ph}=0.1} > 0.01 \text{ ) but not for positive } \left( \left. \frac{\partial [\text{RRP}_2]}{\partial [\text{R}_0]} \right|_{k_{ph}=0.1} > 0.01 \text{ ) but not for positive } \left( \left. \frac{\partial [\text{RRP}_2]}{\partial [\text{R}_0]} \right|_{k_{ph}=0.1} > 0.01 \text{ ) but not for positive } \left( \left. \frac{\partial [\text{RRP}_2]}{\partial [\text{R}_0]} \right|_{k_{ph}=0.1} > 0.01 \text{ ) but not for positive } \left( \left. \frac{\partial [\text{RRP}_2]}{\partial [\text{R}_0]} \right|_{k_{ph}=0.1} > 0.01 \text{ ) but not for positive } \left( \left. \frac{\partial [\text{RRP}_2]}{\partial [\text{R}_0]} \right|_{k_{ph}=0.1} > 0.01 \text{ ) but not for positive } \left( \left. \frac{\partial [\text{RRP}_2]}{\partial [\text{R}_0]} \right|_{k_{ph}=0.1} > 0.01 \text{ ) but not for positive } \left( \left. \frac{\partial [\text{R}_0]}{\partial [\text{R}_0]} \right|_{k_{ph}=0.1} > 0.01 \text{ ) but not for positive } \left( \left. \frac{\partial [\text{R}_0]}{\partial [\text{R}_0]} \right|_{k_{ph}=0.1} > 0.01 \text{ ) but not for positive } \left( \left. \frac{\partial [\text{R}_0]}{\partial [\text{R}_0]} \right|_{k_{ph}=0.1} > 0.01 \text{ ) but not for positive } \left( \left. \frac{\partial [\text{R}_0]}{\partial [\text{R}_0]} \right|_{k_{ph}=0.1} > 0.01 \text{ ) but not for positive } \left( \left. \frac{\partial [\text{R}_0]}{\partial [\text{R}_0]} \right|_{k_{ph}=0.1} > 0.01 \text{ ) but not for positive } \left( \left. \frac{\partial [\text{R}_0]}{\partial [\text{R}_0]} \right|_{k_{ph}=0.1} > 0.01 \text{ ) but not for positive } \left( \left. \frac{\partial [\text{R}_0]}{\partial [\text{R}_0]} \right|_{k_$$

dependent overshoot have effectively negative feedback (Figure S3C). Interestingly, the model frequently predicted significant overshoot for low negative open-loop gains. We conclude that extensive parameter sampling supports our conclusions.

<sup>&</sup>lt;sup>1</sup> For clarity we only focused on the cases with absolute value of open loop-gains larger than 1% to discard the large number of cases with effectively zero open-loop gain.