Supporting Information S1 Fig for

**Predicting precision grip grasp locations on three-dimensional objects**

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(a) Experiment 1

![Experiment 1](image_url)
(b) Experiment 2

Human

Unfitted Model

Fitted Model
S1 Fig. Human and model grasping patterns for Experiments 1 and 2. Grasping patterns from human participants (left), unfitted model (middle), and fitted model (right). (a) Grasping patterns on wooden objects from Experiment 1. (b) Grasping patterns on mixed material objects from Experiment 2.