PLOS Computational Biology

CORRECTION

Correction: Success-efficient/failure-safe strategy for hierarchical reinforcement motor learning

The *PLOS Computational Biology* Staff

S4 Fig was uploaded incorrectly. Please see the correct S4 Fig here.

Supporting information

S4 Fig. Trials at which adaptation measures reached plateaus. Trial numbers and standard deviations of when the Number of Failed Trials, Trajectory Area, Initial Trajectory Area, Co-Contraction, and Smoothness reached their respective plateaus. (PDF)

The publisher apologizes for the error.

Reference

1. Babič J, Kunavar T, Oztop E, Kawato M. Success-efficient/failure-safe strategy for hierarchical reinforcement motor learning. PLoS Comput Biol. 2025;21(5):e1013089. https://doi.org/10.1371/journal.pcbi.1013089 PMID: 40344154

Citation: The *PLOS Computational Biology* Staff (2025) Correction: Success-efficient/failure-safe strategy for hierarchical reinforcement motor learning. PLoS Comput Biol 21(9): e1013537. https://doi.org/10.1371/journal.pcbi.1013537

Published: September 30, 2025