

CORRECTION

## Correction: Success-efficient/failure-safe strategy for hierarchical reinforcement motor learning

The *PLOS Computational Biology* Staff

[S4 Fig](#) was uploaded incorrectly. Please see the correct [S4 Fig](#) here.

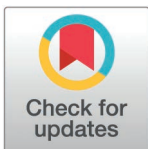
### Supporting information

**S4 Fig. Trials at which adaptation measures reached plateaus.** Trial numbers and standard deviations of when the Number of Failed Trials, Trajectory Area, Initial Trajectory Area, Co-Contraction, and Smoothness reached their respective plateaus. (PDF)

The publisher apologizes for the error.

### Reference

1. Babič J, Kunavar T, Oztop E, Kawato M. Success-efficient/failure-safe strategy for hierarchical reinforcement motor learning. *PLoS Comput Biol*. 2025;21(5):e1013089. <https://doi.org/10.1371/journal.pcbi.1013089> PMID: 40344154



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