Appendix A: Proof of (12)

The solution to the minimization in the first line of (11) is obviously given by

$$\boldsymbol{\alpha}_{n+1} = \boldsymbol{A}^{-1} \left[\mu \boldsymbol{\Psi} \boldsymbol{F}^* \boldsymbol{U}^* (\boldsymbol{y} + \boldsymbol{h}_n) + \rho(\boldsymbol{z}_n + \boldsymbol{d}_n) \right],$$

where

$$\boldsymbol{A} = \boldsymbol{\mu} \boldsymbol{\Psi} \boldsymbol{F}^* \boldsymbol{U}^* \boldsymbol{U} \boldsymbol{F} \boldsymbol{\Psi}^* + \beta (\boldsymbol{I} - \boldsymbol{\Psi} \boldsymbol{\Psi}^*) + \rho \boldsymbol{I}. \tag{14}$$

The key step of this proof is to derive the inversion of matrix A. We will use the Sherman-Morrison-Woodbury matrix inversion formula [36]

$$(X + YZ)^{-1} = X^{-1} - X^{-1}Y(I + ZX^{-1}Y)^{-1}ZX^{-1}$$
(15)

provided that $(I + ZX^{-1}Y)$ is invertible. We will consider the inverse of the last two terms in (14) as follows

$$\boldsymbol{B} = \beta (\boldsymbol{I} - \boldsymbol{\Psi} \boldsymbol{\Psi}^*) + \rho \boldsymbol{I} = (\beta + \rho) \boldsymbol{I} - \beta \boldsymbol{\Psi} \boldsymbol{\Psi}^*.$$

Using (15) and the property of a tight frame, we get

$$\boldsymbol{B}^{-1} = \left((\beta + \rho)\boldsymbol{I} - \beta\boldsymbol{\Psi}\boldsymbol{\Psi}^* \right)^{-1} = \frac{1}{\beta + \rho}\boldsymbol{I} + \frac{\beta}{\beta + \rho}\boldsymbol{\Psi} \left(\boldsymbol{I} - \boldsymbol{\Psi}^* \frac{\beta}{\beta + \rho}\boldsymbol{\Psi} \right)^{-1} \boldsymbol{\Psi}^* \frac{1}{\beta + \rho} = \frac{1}{\beta + \rho}\boldsymbol{I} + \frac{\beta}{\rho(\beta + \rho)}\boldsymbol{\Psi}\boldsymbol{\Psi}^*,$$
(16)

where we have used the tight frame property $\Psi^*\Psi = I$. Then, by using the Sherman-Morrison-Woodbury matrix inversion formula (15) again, the inverse of A in (14) is

$$A^{-1} = (B + \mu \Psi F^* U^* U F \Psi^*)^{-1} = B^{-1} - B^{-1} \mu \Psi F^* U^* (I + U F \Psi^* B^{-1} \mu \Psi F^* U^*)^{-1} U F \Psi^* B^{-1}.$$
 (17)

Moreover, (16) implies

$$(\boldsymbol{I} + \boldsymbol{U}\boldsymbol{F}\boldsymbol{\Psi}^*\boldsymbol{B}^{-1}\boldsymbol{\mu}\boldsymbol{\Psi}\boldsymbol{F}^*\boldsymbol{U}^*)^{-1} = \left(\boldsymbol{I} + \boldsymbol{U}\boldsymbol{F}\boldsymbol{\Psi}^*\left(\frac{1}{\beta+\rho}\boldsymbol{I} + \frac{\beta}{\rho(\beta+\rho)}\boldsymbol{\Psi}\boldsymbol{\Psi}^*\right)\boldsymbol{\mu}\boldsymbol{\Psi}\boldsymbol{F}^*\boldsymbol{U}^*\right)^{-1} = \frac{\rho}{\rho+\mu}\boldsymbol{I}.$$

This together with (17) leads to

$$\begin{aligned} \boldsymbol{A}^{-1} &= \frac{1}{\beta + \rho} \boldsymbol{I} + \frac{\beta}{\rho(\beta + \rho)} \boldsymbol{\Psi} \boldsymbol{\Psi}^* - \frac{\mu}{\rho(\mu + \rho)} \boldsymbol{\Psi} \boldsymbol{F}^* \boldsymbol{U}^* \boldsymbol{U} \boldsymbol{F} \boldsymbol{\Psi}^* \\ &= \frac{1}{\rho} \left[\gamma \boldsymbol{I} + (1 - \gamma) \boldsymbol{\Psi} \boldsymbol{\Psi}^* - \frac{\mu}{\mu + \rho} \boldsymbol{\Psi} \boldsymbol{F}^* \boldsymbol{U}^* \boldsymbol{U} \boldsymbol{F} \boldsymbol{\Psi} \right] \end{aligned}$$

where we have used $\gamma = \frac{\rho}{\beta + \rho}$ to the role of the balancing parameter β . Finally, the solution of Eq. (17) is

$$\begin{aligned} \boldsymbol{\alpha}_{n+1} &= \boldsymbol{A}^{-1} \left[\mu \boldsymbol{\Psi} \boldsymbol{F}^* \boldsymbol{U}^* (\boldsymbol{y} + \boldsymbol{h}_n) + \rho(\boldsymbol{z}_n + \boldsymbol{d}_n) \right] \\ &= \frac{1}{\rho} \left[\gamma \boldsymbol{I} + (1 - \gamma) \boldsymbol{\Psi} \boldsymbol{\Psi}^* - \frac{\mu}{\mu + \rho} \boldsymbol{\Psi} \boldsymbol{F}^* \boldsymbol{U}^* \boldsymbol{U} \boldsymbol{F} \boldsymbol{\Psi} \right] \left[\mu \boldsymbol{\Psi} \boldsymbol{F}^* \boldsymbol{U}^* (\boldsymbol{y} + \boldsymbol{h}_n) + \rho(\boldsymbol{z}_n + \boldsymbol{d}_n) \right] \\ &= \frac{\mu}{\mu + \rho} \boldsymbol{\Psi} \boldsymbol{F}^* \boldsymbol{U}^* (\boldsymbol{y} + \boldsymbol{h}_n) + \gamma(\boldsymbol{z}_n + \boldsymbol{d}_n) + \boldsymbol{\Psi} \boldsymbol{F}^* \left[(1 - \gamma) \boldsymbol{I} - \frac{\mu}{\mu + \rho} \boldsymbol{U}^* \boldsymbol{U} \right] \boldsymbol{F} \boldsymbol{\Psi}^* (\boldsymbol{z}_n + \boldsymbol{d}_n), \end{aligned}$$

which concludes the proof.