

parameter	description	value/s
<i>bites</i>	the number of food units to be consumed throughout the simulation	100-100,000 [food-units]
<i>mean patch quality</i>	the mean Poisson distributed number of food units available in a new patch; the quality of landscape.	100 [food-units/patch]
<i>presumed mean patch quality</i>	the initial belief of the forager regarding the landscape quality; values >100 correspond to ‘optimism’ while values <100 correspond to ‘pessimism’.	25-175 [food-units/patch]
<i>mean travel time</i>	the mean exponentially distributed travel time across the landscape; the average time required to locate a new patch.	10 [time-units]
<i>food growth rate</i>	the logistic renewal rate of food patches	0.001 [time-units ⁻¹]
<i>handling time</i>	the time required to process a single food unit	1 [time-units]
<i>search rate</i>	the fraction of a patch covered by the forager during each time spent searching for food.	0.01 [patch/time-units]
θ	the linear operator determining the rate of information update. If $\theta = 0$ the forager never learns and thus maintain its initial beliefs throughout the simulation; if $\theta = 1$ the forager would believe the mean patch quality is equal to those characterising its current location.	0.01