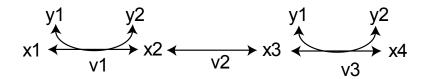
Supplement: An Illustrative example of modal decomposition for a toy network.

Consider a simple 'toy' group of reactions given by,



These three reactions and six metabolites can be described by a 6x3 stoichiometric matrix,

(71	ν2	v3
XI	-1	0	
x 2	1	-1	0
x3	0	1	-1
x 4	0	0	1
1 1 1	-1	0	-1
y2 (1	0	1)

Ascribing equilibrium constants to the reactions and forward rate constants, the mass action rate expressions immediately follow.

Equilibrium constants Forward rate con	stants Rate equations
v1 100 1.3	0.26x1-0.026x2
V1 100 1.3 V2 2 100 000 V3 100 0.3	100000 x2 - 50000 x3
v3 100 0.3	0.06x3-0.006x4

Having defined the stoichiometric matrix and the rate equations, a particular steady state can be solved for. In this example we set the concentration of x3 to 0.5 mM, thereby fixing the network at a particular steady state given by,

	mΜ		
(X1	0.025)		
x 2	0.25		
x3	0.5		
x 4	5.		
y1	0.2		
y2	2)		

Defining the deviation variables as $x' = x - x_{ss}$, with x_{ss} referring to a steady state vector. After linearizing around a steady state,

$$\frac{dx'}{dt} = Jx'$$

in which J is the Jacobian. For the above toy system this equation,

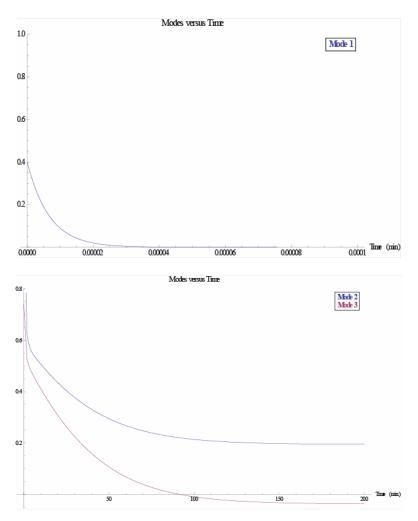
		(-0.26	0.026	0	0	-0.0325	0.00325	(x1)
		0.26	-100000.	50 000	0	0.0325	-0.00325	x2
dy'/dt		0	100 000	-50000.1	0.006	-0.15	0.015	X3
ux/ut	_	0	0	0.06	-0.006	0.15	-0.015	X4
		-0.26	0.026	-0.06	0.006	-0.1825	0.01825	y1
		0.26	-0.026	0.06	-0.006	0.1825	-0.01825/	(y2)

Applying a similarity transformation to J and calculating the modal matrix (see equations 2 and 3 in the main text) results in,

1	Time Scales (min)	x1	x 2	x 3	x 4	у1	y2
	6.66667×10-6	1.73334×10-6	-1.	0.5	-2.×10 ⁻⁸	7.16668×10-7	-7.16668×10 ⁻⁸
	3.00914	1.	0.00101096	0.00101062	-0.00515161	0.25379	-0.025379
(5.46163	1.	-0.182652	-0.182652	0.0223978	-0.434944	0.0434944)

in which the time scales are the negative reciprocals of the eigenvalues. Note that since the rank of the Jacobian is only 3, there are only 3 modes in this system. From the time scales, one can see that these reactions span about 7 orders of magnitude.

In order to explicitly see visualize the modes, we can plot the relaxation of this systems in response to a perturbation (through integration of equation 4 in the main text).



Mode 1 is plotted separately from Modes 2 and 3 because their dynamic responses take place on significantly different time scales. Full relaxation of Mode 1 takes place on the order of milliseconds, whereas full relaxation of Modes 2 and 3 take place on the order of hours.

Due to the small number of variables and simplicity of this example, the pooling structure can be immediately identified in this example. x2 and x3 immediately equilibrate and move together

across all of the time scales. y1 and y2 pool together after the first time scale, finally to be joined by x1 and x4. The corresponding pooling plot can be seen,

