

Fig. S1. Architecture of task sets. The monitoring buffer comprises a limited number of task sets, each indexing a behavioral strategy stored in long-term memory and comprising: a selective, predictive and contextual mapping (M.). The reliability of each task set is monitored online at two time points: right before acting (ex-ante reliability  $\lambda_i$ ) and right after perceiving action outcomes (ex-post reliability  $\mu_i$ ): ex-ante reliability  $\lambda_i$  is inferred from ex-post reliability in the preceding trial according to contextual cues C (given contextual models) and the perceived volatility of external contingencies (not shown); ex-post reliability  $\mu_i$  is inferred from ex-ante reliability preceding action according to action outcomes r (given predictive models). Ex-ante reliability serves to choose the actor driving immediate behavior. The actor selective mapping then determines the responses to stimuli. Actor selective and predictive mappings learns according to action outcomes. Contextual mappings of task sets adjust to ex-post reliability and consequently learns contextual cues C predicting task set reliability. Red indicates computations occurring within the actor set only. Arrows indicate information flows occuring within task sets. Broken arrows symbolize learning processes within internal mappings (M.). Blue lines represent the associations remaining between internal mappings forming strategies stored in long-term memory and previously indexed by a task set. See Methods for notations.